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Methodology for statistical detection of climate change

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SEAMOCS Workshop







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Detection

Definition, according to the IPCC AR3 :

"Detection is the process of demonstrating that an observed change is significantly different (in a statistical sense) than can be explained by natural internal variability" Introduction • 0 0 Presenting the problem

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Detection

Definition, according to the IPCC AR3 :

"Detection is the process of demonstrating that an observed change is significantly different (in a statistical sense) than can be explained by natural internal variability"

Detection of the anthropogenic climate change :

- Investigation of the presence of a particular signal, given by climate model simulation
- Double objectives :
 - Show the existence of a significant change of the observations
 - Validate the climate models

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Statistical modelisation

Notations :

- ψ : random climate vector, of dimension p, taking one value per year
- C : the covariance matrix of ψ
- g : the climate change vector, of dimension p, given by a model

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- Framework
- Result when C is known
- The problem when C is not known

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- Regularisation
- Bootstrap

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- Climate scenario
- Observations

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Framework

Assumptions

- $(\psi_i)_{i \in \llbracket 1,n \rrbracket} \in \mathbb{R}^p$ rv iid having a N(0,C) distribution
- $\psi_{n+1} \in \mathbb{R}^{p}$, independent of the $(\psi_{i})_{i \in [1,n]}$, having a $N(\mu g, C)$ distribution

With
$$\mu \in \mathbb{R}$$
, $g \in \mathbb{S}^{p-1} \subset \mathbb{R}^p$, and $C \in \mathcal{M}_p(\mathbb{R})$

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, $g \in \mathbb{S}^{p-1} \subset \mathbb{R}^p$, and $C \in \mathcal{M}_p(\mathbb{R})$

Test

One wants to test :

$$H_0$$
 : " $\mu = 0$ " vs H_1 : " $\mu > 0$ "

in large dimension, that is to say $n \sim p$.

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Investigated test family

One considers the following tests $(T_f)_{f \in \mathbb{R}^p}$:

Test variable *d*_f

$$d_f = \langle \psi_{n+1}, f \rangle \quad \sim_{H_0} N(0, f'Cf)$$

Rejection region

$$W_f = \left\{ \psi_{n+1} \in \mathbb{R}^p, d_f = \langle \psi_{n+1}, f \rangle \ge d_f^{(lpha)}
ight\}$$

with

$$d_f^{(\alpha)} = \Phi^{-1}(1-\alpha) \sqrt{f'Cf}$$

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Optimal *T*_{*f*}

Question

Knowing C and g, is there an optimal T_f ?

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Optimal *T*_{*f*}

Question

Knowing C and g, is there an optimal T_f ?

Answer : yes

 $T_{C^{-1}g}$ is optimal, among the (T_f) , within the following meaning

- $d_{C^{-1}g}$ maximise the signal-to-noise
- $T_{C^{-1}g}$ is the most powerful test
- $T_{C^{-1}g}$ is the likelihood ratio test

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In the case "C unknown", one wants to approximate $T_{C^{-1}g}$. Two new test families are considered.

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In the case "C unknown", one wants to approximate $T_{C^{-1}g}$. Two new test families are considered.

 \mathcal{T}_f tests

- f is "estimated" : depending on (ψ_i)_{i∈[[1,n]]}, that are random, and on g
- The level, conditionally to $(\psi_i)_{i \in \llbracket 1,n \rrbracket}$, is nominal;
 - *C* is known, only for computing $d_f^{(\alpha)} = \Phi^{-1}(1-\alpha) \sqrt{f'Cf}$

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In the case "C unknown", one wants to approximate $T_{C^{-1}g}$. Two new test families are considered.

 \mathcal{T}_f tests

\mathbb{T}_f tests

- f is estimated
- The threshold d^(α)_f is estimated depending on g and (ψ_i)_{i∈[[1,n]]}; in the same way for the p-value
- The level is not necessarily nominal

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\mathbb{T}_f tests			
Naive te	est : T_g		

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Problem when *C* **is not known**

Objectives

One wants to construct a \mathbb{T}_f test having "good" properties :

- Nominal level
- A power greater than the one of the naive test T_g

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Problem when *C* **is not known**

Objectives

One wants to construct a \mathbb{T}_f test having "good" properties :

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- A power greater than the one of the naive test T_g

Remark

It is possible to firstly study \mathcal{T}_f , noticing that " $\mathcal{T}_f > \mathbb{T}_f$ "

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Using the empirical covariance matrix

$$\hat{C} = \frac{1}{n} \sum_{i=1}^{n} \psi_i \psi'_i$$

Does $\mathcal{T}_{\hat{\mathcal{C}}^{-1}g}$ have good properties ?

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Using the empirical covariance matrix

$$\hat{C} = \frac{1}{n} \sum_{i=1}^{n} \psi_i \psi'_i$$

Does $\mathcal{T}_{\hat{\mathcal{C}}^{-1}g}$ have good properties ?

No ! (\hat{C} is quasi-singular) The use of a pseudo-inverted truncation of \hat{C} doesn't give an efficient test either

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Regularisation in our case : shrinkage

Main idea

One uses $\gamma \hat{C} + \rho I_p$ instead of \hat{C} .

Justification

- Interpolation with the naive test T_g
- Ridge regression point of view

• Power of the tests
$$\mathcal{T}_{\left(\gamma\hat{\mathcal{C}}+
ho I_{
ho}
ight)^{-1}g}$$

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Estimation of the parameters (γ, ρ)

Optimal shrinkage method (O. Ledoit, *A Well-Conditioned Estimator for Large Dimensional Covariance Matrices*)

Framework :

• One reasons on $\mathcal{M}_{\rho}(\mathbb{R})$ with the norm

$$\|A\|_{\mathcal{M}_p}^2 = \frac{\mathrm{Tr}(AA')}{p}$$

- A "general asymptotics" framework is used : $n, p_n, \frac{p_n}{n} \leq K$
- Estimators of the following family are investigated $C^* = \gamma \hat{C} + \rho I_p$. One researches the C^* minimising :

$$\mathsf{E}\left(\|C^*-C\|^2_{\mathcal{M}_p}
ight)$$

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Estimation of the parameters (γ, ρ)

Optimal shrinkage method (O. Ledoit, *A Well-Conditioned Estimator for Large Dimensional Covariance Matrices*)

n fixed : optimal γ_n^0 and ρ_n^0 depending on *C*

$$\gamma_n^0 = \frac{\alpha^2}{\delta^2}, \quad \text{and} \quad \rho_n^0 = \frac{\beta^2 \nu}{\delta^2}$$

where

$$\nu = \langle C, I_p \rangle_{\mathcal{M}_p} = \frac{\operatorname{Tr}(C)}{p}, \qquad \alpha^2 = \|C - \nu I_p\|_{\mathcal{M}_p}^2,$$
$$\beta^2 = \mathsf{E}\left(\|\hat{C} - C\|_{\mathcal{M}_p}^2\right), \qquad \delta^2 = \mathsf{E}\left(\|\hat{C} - \nu I_p\|_{\mathcal{M}_p}^2\right),$$

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Estimation of the parameters (γ, ρ)

Optimal shrinkage method (O. Ledoit, A Well-Conditioned Estimator for Large Dimensional Covariance Matrices)

n fixed : optimal γ_n^0 and ρ_n^0 depending on *C*

Under "general asymptotics" : convergent estimators $\hat{\gamma}^0_n$ and $\hat{\rho}^0_n$ of γ^0_n and ρ^0_n

$$\hat{\gamma} = \frac{\hat{\alpha}^2}{\hat{\delta}^2}, \quad \text{and} \quad \hat{\rho} = \frac{\beta^2 \hat{\nu}}{\hat{\delta}^2}$$
Vith
$$\hat{r} = \langle \hat{C}, I_p \rangle_{\mathcal{M}_p} = \frac{\text{Tr}(\hat{C})}{p}, \quad \hat{\beta}^2 = \min\left(\hat{\delta}^2, \frac{1}{n^2} \sum_{i=1}^n \|\psi_i \psi_i' - \hat{C}\|_{\mathcal{M}_p}^2\right)$$

$$\hat{\delta}^2 = \|\hat{C} - \hat{\nu}I_p\|_{\mathcal{M}_p}^2, \quad \hat{\alpha}^2 = \hat{\delta}^2 - \hat{\beta}^2.$$

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Estimation of the parameters (γ, ρ)

Optimal shrinkage method (O. Ledoit, A Well-Conditioned Estimator for Large Dimensional Covariance Matrices)

n fixed : optimal γ_n^0 and ρ_n^0 depending on *C*

Under "general asymptotics" : convergent estimators $\hat{\gamma}^0_n$ and $\hat{\rho}^0_n$ of γ^0_n and ρ^0_n

A new estimator of C is defined :

$$\hat{C}_I = \hat{\gamma}^0_n \hat{C} + \hat{\rho}^0_n I_p$$

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Bootstrap's motivations

One has to achieve the construction of $\mathbb{T}_{\hat{\mathcal{C}}_{\iota}^{-1}g},$ by :

- computing the test threshold (and more generally the *p*-value),
- verifying that this computation is correct, or that the level is close to the nominal value,
- computing the power.

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Additional treatment

- Choice of a learning sample,
- Temporal treatment (mobile average),
- Spatial centering.



Figure: Summer minimum temperatures in the model : Comparison between the naive test T_g and the optimal regularised $\mathbb{T}_{\hat{C}_l^{-1}g}$ for summer minimum temperatures taken from a climate scenario.



Figure: Summer temperatures in observations : Results for minimum and maximum temperatures

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Questions